

PROBLEM 3.1

$$(a) \quad y(t) = h(t) * x(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$(i) \quad x(t) = u(t-2)$$

$$y(t) = \int_{-\infty}^{\infty} u(\tau-2) u(t-\tau) d\tau = \int_2^t 1 d\tau$$

$$y(t) = \begin{cases} 0, & t < 2 \\ t-2, & t \geq 2 \end{cases} = (t-2)u(t-2)$$

$$(ii) \quad x(t) = e^{-2t} u(t)$$

$$y(t) = \int_{-\infty}^{\infty} e^{-2\tau} u(\tau) u(t-\tau) d\tau = \int_0^t e^{-2\tau} d\tau$$

$$y(t) = \frac{1}{2}(1 - e^{-2t}) u(t)$$

$$(iii) \quad x(t) = t u(t)$$

$$y(t) = \int_{-\infty}^{\infty} \tau u(\tau) u(t-\tau) d\tau = \int_0^t \tau d\tau = \frac{1}{2} \tau^2 \Big|_0^t$$

$$y(t) = \frac{1}{2} t^2 u(t)$$

$$(iv) \quad x(t) = (t+1) u(t+1)$$

$$y(t) = \int_{-\infty}^{\infty} (\tau+1) u(\tau+1) u(t-\tau) d\tau = \int_{-1}^t (\tau+1) d\tau$$

$$= \left(\frac{1}{2} \tau^2 + \tau \right) \Big|_{-1}^t = \frac{1}{2} t^2 + t - \frac{1}{2} + 1$$

$$y(t) = \left(\frac{1}{2} t^2 + t + \frac{1}{2} \right) u(t+1)$$

$$(v) \quad x(t) = e^{-2|t|} ; \quad y(t) = \int_{-\infty}^{\infty} e^{-2|\tau|} u(t-\tau) \tau d\tau$$

$$y(t) = \int_{-\infty}^t e^{-2|\tau|} d\tau$$

$$\text{for } t < 0, \quad y(t) = \int_{-\infty}^0 e^{2\tau} d\tau = \frac{1}{2} e^{2t}, \quad t < 0$$

$$\text{for } t \geq 0, \quad y(t) = \int_{-\infty}^0 e^{2\tau} d\tau + \int_0^t e^{-2\tau} d\tau = 1 - \frac{1}{2} e^{-2t}, \quad t \geq 0$$

Problem 3.1 (Continued)

(a) (vi) $x(t) = t^2 u(t) \Rightarrow y(t) = \int_0^t \tau^2 d\tau = \frac{1}{3} t^3 u(t)$

(vii) $x(t) = (t-1)u(t-1)$
 $y(t) = \int_1^t (\tau-1) d\tau = \left(\frac{1}{2} \tau^2 - \tau \right) \Big|_1^t = \frac{1}{2} t^2 - t + \frac{1}{2} + 1$
 $y(t) = \left(\frac{1}{2} t^2 - t + \frac{1}{2} \right) u(t-1)$

(viii) $x(t) = u(t) - u(t-5)$

$$y(t) = \int_0^t d\tau - \int_5^t d\tau = \tau \Big|_0^t - \tau \Big|_5^t$$

$$y(t) = t - t + 5 = 5, \quad t \geq 5$$

$$y(t) = t, \quad 0 \leq t < 5$$

$$y(t) = 0, \quad t < 0$$

$$\therefore y(t) = t u(t) + (5-t) u(t-5)$$

(b) (i) $y(t) = \int_{-\infty}^t x(\tau) d\tau = \int_{-\infty}^t u(\tau-2) d\tau = \int_2^t d\tau$

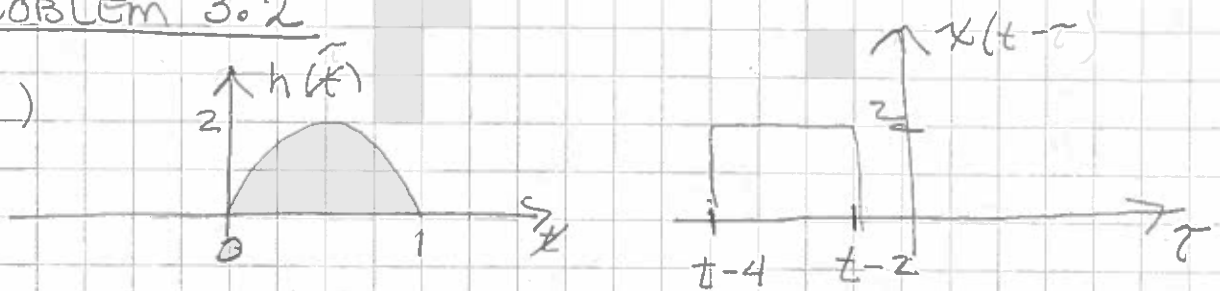
$$y(t) = \begin{cases} 0, & t < 2 \\ t-2, & t \geq 2 \end{cases} = (t-2)u(t-2)$$

(ii) $y(t) = \int_{-\infty}^t e^{-2\tau} u(\tau) d\tau = \int_0^t e^{-2\tau} d\tau = \frac{1}{2} e^{-2\tau} \Big|_0^t, \quad t \geq 0$

$$y(t) = -\frac{1}{2} e^{-2t} + \frac{1}{2}, \quad t \geq 0 = \frac{1}{2} (1 - e^{-2t}) u(t)$$

PROBLEM 3.2

(a)



$$y(t) = 4 \int_0^{t-2} \sin \pi \tau d\tau = -\frac{4}{\pi} \cos \pi \tau \Big|_0^{t-2}$$

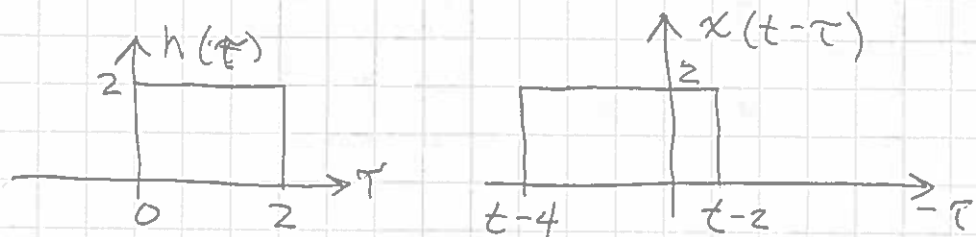
$$= -\frac{4}{\pi} [1 - \cos \pi(t-2)], \quad 2 < t < 3$$

$$y(t) = 4 \int_0^1 \sin \pi t dt = -\frac{4}{\pi} \cos \pi t \Big|_0^1 = \frac{8}{\pi}, \quad 3 \leq t \leq 4$$

$$y(t) = 4 \int_{t-4}^1 \sin \pi \tau d\tau = \frac{4}{\pi} [\cos \pi(t-4) + 1], \quad 4 < t < 5$$

$$y(t) = 0, \quad t < 2 \quad \text{and} \quad t > 5$$

(b)

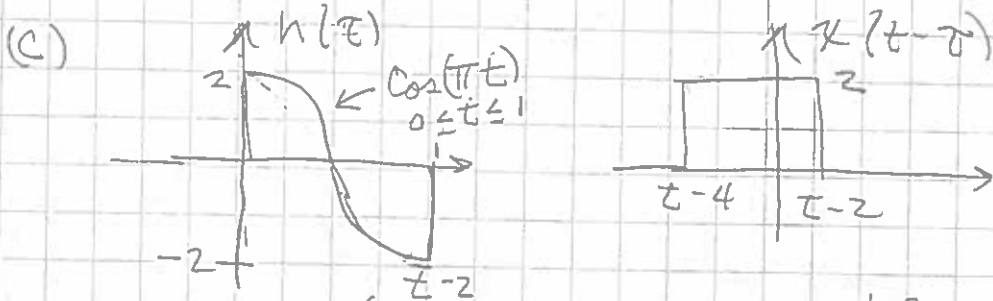


$$y(t) = 4 \int_0^{t-2} d\tau = 4\tau \Big|_0^{t-2} = 4t - 8, \quad 2 \leq t < 4$$

$$y(t) = 4 \int_{t-4}^2 d\tau = 4\tau \Big|_{t-4}^2 = 24 - 4t, \quad 4 \leq t < 6$$

$$y(t) = 0, \quad t < 2, \quad \text{and} \quad t > 6$$

Problem 3.2 (continued)

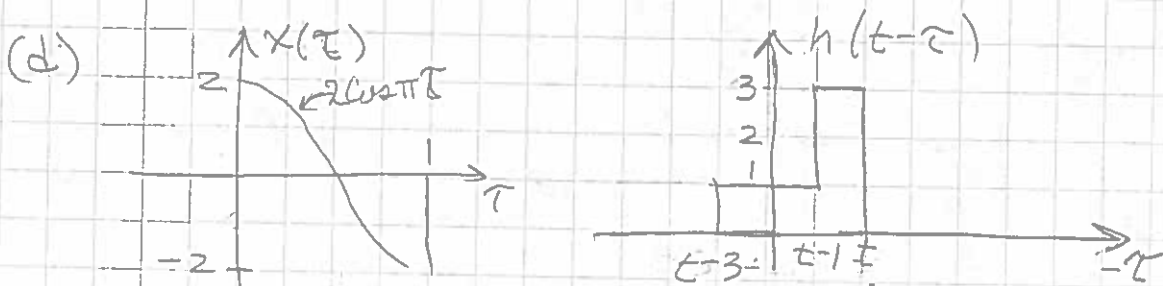


$$y(t) = 4 \int_0^{t-2} \cos(\pi\tau) d\tau = \frac{4}{\pi} \sin \pi\tau \Big|_0^{t-2} = \frac{4}{\pi} \sin \pi(t-2), 0 < t < 1$$

$$y(t) = 4 \int_0^1 \cos \pi\tau d\tau = \frac{4}{\pi} \sin \pi\tau \Big|_0^1 = 0, 1 \leq t < 4$$

$$y(t) = 4 \int_{t-4}^1 \cos \pi\tau d\tau = \frac{4}{\pi} \sin \pi\tau \Big|_{t-4}^1 = -\frac{4}{\pi} \sin \pi(t-4), 4 < t < 5$$

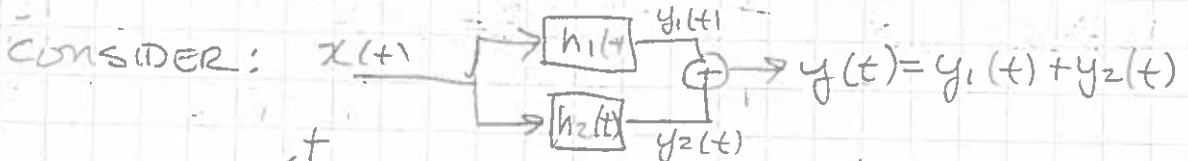
$$y(t) = 0, t < 0 \text{ and } t > 5$$



let $h(t) = h_1(t) + h_2(t)$

$$h_1(t) = 2[u(t) - u(t-1)]$$

$$h_2(t) = u(t) - u(t-3)$$



$$y_1(t) = \int_0^t 4 \cos \pi\tau d\tau = \frac{4}{\pi} \sin \pi\tau \Big|_0^t = \frac{4}{\pi} \sin \pi t, 0 \leq t < 1$$

$$= \int_{t-1}^1 4 \cos \pi\tau d\tau = \frac{4}{\pi} \sin \pi\tau \Big|_{t-1}^1 = -\frac{4}{\pi} \sin \pi(t-1), 1 < t < 2$$

$$y_1(t) = 0, t < 0, t > 2$$

PROBLEM 3.2 (d) (continued)

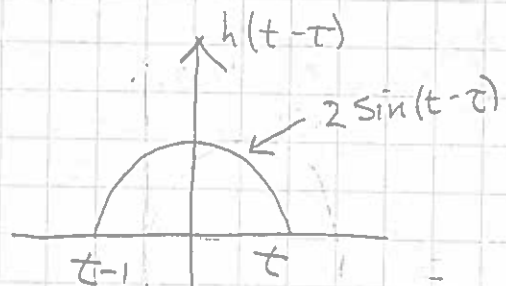
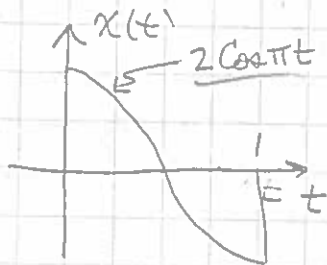
$$\begin{aligned}
 y_2(t) &= \int_0^t 2 \cos \pi \tau d\tau = \frac{2}{\pi} \sin \pi \tau \Big|_0^t = \frac{2}{\pi} \sin \pi t, \quad 0 < t < 1 \\
 &= \int_0^1 2 \cos \pi \tau d\tau = \frac{2}{\pi} \sin \pi \tau \Big|_0^1 = 0, \quad 1 < t < 2 \\
 &= \int_{t-2}^1 2 \cos \pi \tau d\tau = \frac{2}{\pi} \sin \pi \tau \Big|_{t-2}^1 = -\frac{2}{\pi} \sin \pi (t-2), \quad 2 < t < 3
 \end{aligned}$$

$$y_2(t) = 0, \quad t < 0, \quad t > 3$$

$$y(t) = y_1(t) + y_2(t)$$

$$y(t) = \begin{cases} 0, & t < 0 \\ \frac{4}{\pi} \sin \pi t, & 0 < t < 1 \\ -4 \sin \pi (t-1), & 1 < t < 2 \\ -2 \sin \pi (t-2), & 2 < t < 3 \\ 0, & t > 3 \end{cases}$$

(e)



$0 < t < 1$

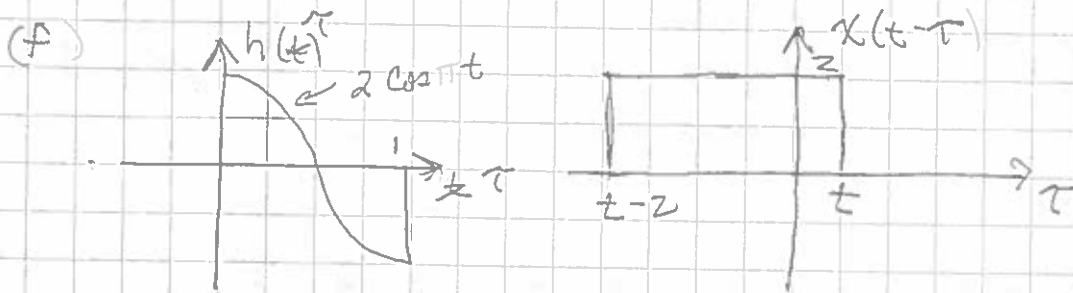
$$\begin{aligned}
 y(t) &= \int_0^t 4 \sin \pi \tau \cos \pi \tau d\tau = 2 \int_0^t \sin 2\pi \tau d\tau \\
 &= \frac{-2}{2\pi} \cos 2\pi \tau \Big|_0^t = 1 - \frac{1}{\pi} \cos 2\pi t, \quad 0 < t < 1
 \end{aligned}$$

$1 < t < 2$

$$y(t) = \int_{t-1}^1 2 \sin 2\pi \tau d\tau = -\frac{1}{\pi} \cos \pi \tau \Big|_{t-1}^1 = -1 + \frac{1}{\pi} \cos \pi (t-1), \quad 1 < t < 2$$

$$y(t) = 0, \quad t < 0, \quad t > 2$$

PROBLEM 3.2 (continued)



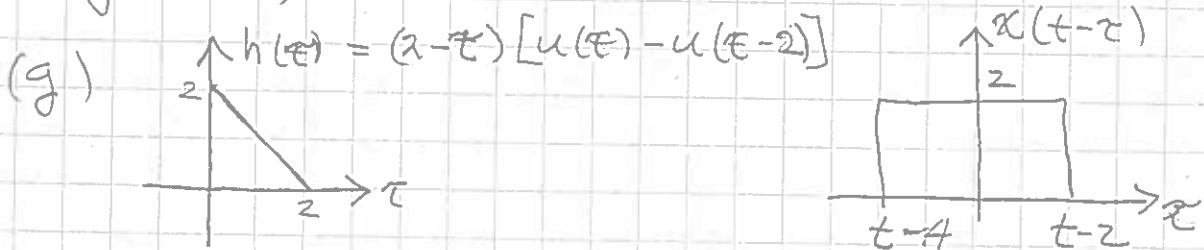
$$y(t) = 0, t < 0$$

$$\underline{0 < t < 1}: y(t) = \int_0^t 4 \cos \pi \tau d\tau = \frac{4}{\pi} \sin \pi \tau \Big|_0^t = \frac{4}{\pi} \sin \pi t, \underline{0 < t < 1}$$

$$\underline{1 < t < 2}: y(t) = \int_0^1 4 \cos \pi \tau d\tau = \frac{4}{\pi} \sin \pi \tau \Big|_0^1 = 0$$

$$\underline{2 < t < 3}: y(t) = \int_{t-2}^1 4 \cos \pi \tau d\tau = \frac{4}{\pi} \sin \pi \tau \Big|_{t-2}^1 = -\frac{4}{\pi} \sin \pi (t-2), \underline{2 < t < 3}$$

$$y(t) = 0, t > 3$$



$$y(t) = 0, t < 2$$

$$\underline{2 < t < 4}: y(t) = 2 \int_0^{t-2} (2-\tau) d\tau = (4\tau - \tau^2) \Big|_0^{t-2}$$

$$y(t) = 4(t-2) - (t-2)^2 = -t^2 + 8t - 12, \underline{2 < t < 4}$$

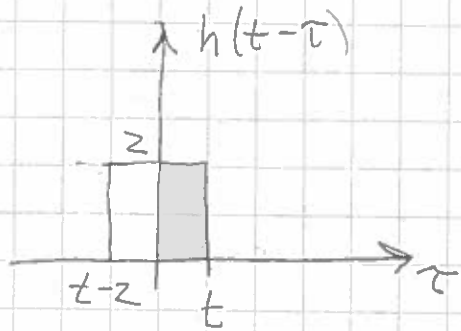
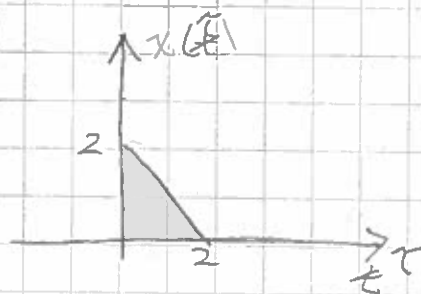
$$\underline{4 < t < 6}: y(t) = 2 \int_{t-4}^2 (2-\tau) d\tau = (4\tau - \tau^2) \Big|_{t-4}^2 = (8-4) - [4t-16 - (t-4)^2]$$

$$= 4 - 4t + 16 + t^2 - 8t + 16 = t^2 - 12t + 36, \underline{4 < t < 6}$$

$$y(t) = 0, t > 6$$

PROBLEM 3.2 (Continued)

(A)



$$y(t) = 0, \quad t < 0$$

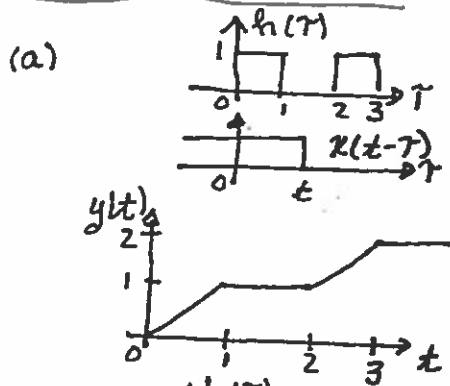
$$0 < t < 2: \quad y(t) = 2 \int_0^t (2-\tau) d\tau = 4\tau - \tau^2 \Big|_0^t = 4t - t^2$$

$$2 < t < 4: \quad y(t) = 2 \int_{t-2}^2 (2-\tau) d\tau = 4\tau - \tau^2 \Big|_{t-2}^2$$

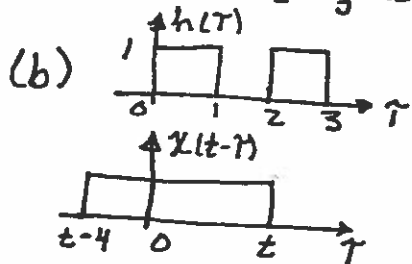
$$y(t) = (8 - 4) - [4(t-2) - (t-2)^2] = t^2 - 8t + 16, \quad 2 < t < 4$$

$$y(t) = 0, \quad t > 4$$

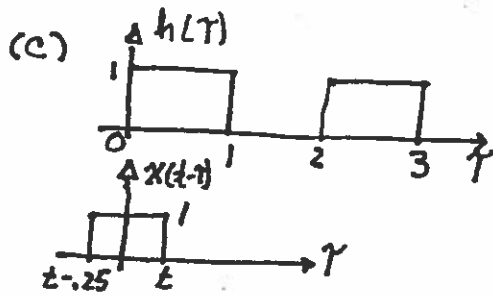
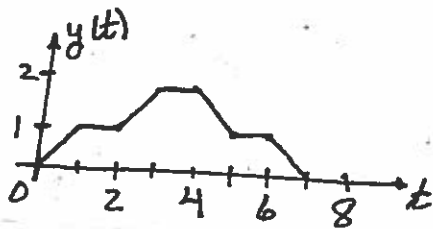
PROBLEM 3.3



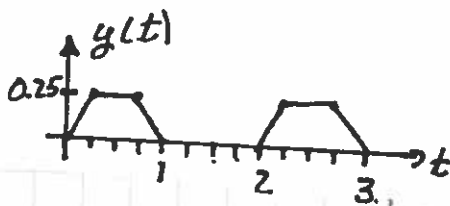
$$\begin{aligned}
 y(t) &= 0, t < 0 \\
 &= t, 0 < t < 1 \\
 &= 1, 1 < t < 2 \\
 &= 1 + (t-2) = t-1, 2 < t < 3 \\
 &= 2, 3 < t
 \end{aligned}$$



range	$y(t)$
$t < 0$	0
$0 < t < 1$	t
$1 < t < 2$	1
$2 < t < 3$	$1-t$
$3 < t < 4$	2
$4 < t < 5$	$2-(t-4) = 6-t$
$5 < t < 6$	1
$6 < t < 7$	$1-(t-6) = 7-t$
$t > 7$	0

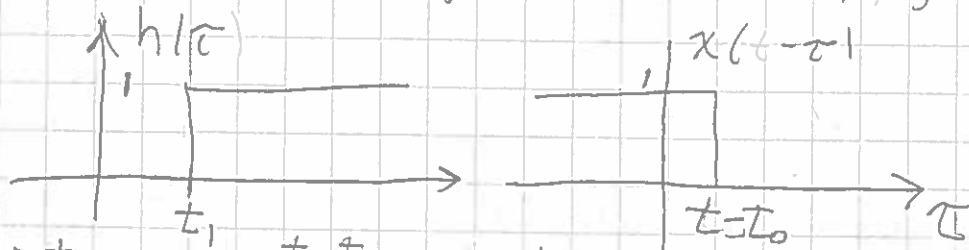


range	$y(t)$
$t < 0$	0
$0 < t < 0.25$	t
$0.25 < t < 1$	0.25
$1 < t < 1.25$	$0.25-(t-1) = 1.25-t$
$1.25 < t < 2$	0
$2 < t < 2.25$	$t-2$
$2.25 < t < 3$	0.25
$3 < t < 3.25$	$3.25-t$
$3.25 < t$	0



PROBLEM 3.4

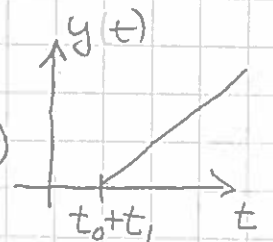
$$x(t) = u(t-t_0), \quad h(t) = u(t-t_1), \quad t_1 > t_0$$



$$y(t) = \int_{t_1}^{t-t_0} d\tau = \tau \Big|_{t_1}^{t-t_0} = t-t_0-t_1, \quad t > t_0+t_1$$

$$y(t) = 0, \quad t < t_0+t_1$$

$$y(t) = (t-t_0-t_1)u(t-t_0-t_1)$$

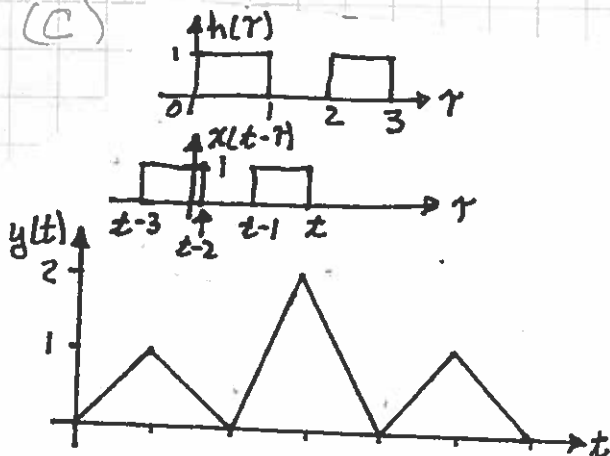


Problem 3.5

(a) See solution for problem 3.3 (b)

(b) See solution for Problem 3.3 (c)

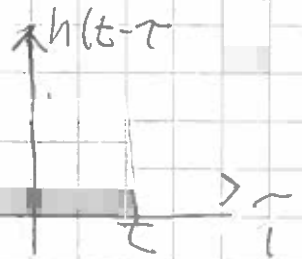
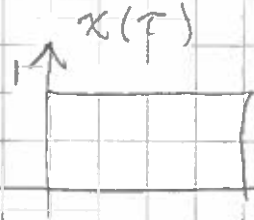
(c)



range	y(t)
$t < 0$	0
$0 < t < 1$	t
$1 < t < 2$	2-t
$2 < t < 3$	2(t-2)
$3 < t < 4$	2(4-t)
$4 < t < 5$	t-4
$5 < t < 6$	6-t
$6 < t$	0

prob BL CM 3.5 (continued)

(d)

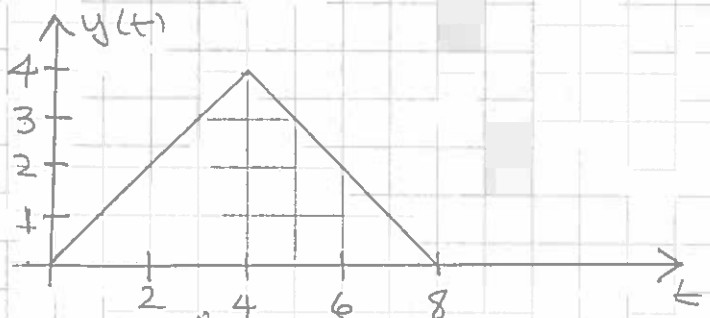


$y(t) = 0, t < 0$

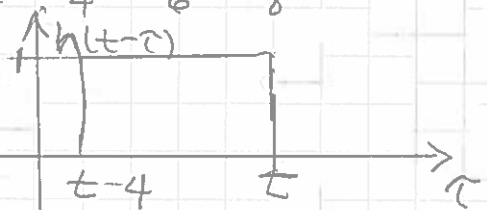
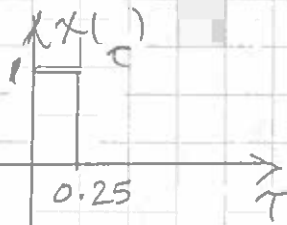
$0 < t < 4: y(t) = \int_0^t d\tau = \tau \Big|_0^t = t, 0 < t < 4$

$4 < t < 8: y(t) = \int_{t-4}^4 d\tau = \tau \Big|_{t-4}^4 = 4 - t + 4 = 8 - t, 4 < t < 8$

$y(t) = 0, t > 8$



(e)



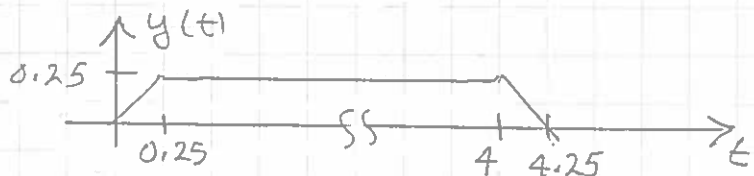
$y(t) = 0, t < 0$

$0 < t < 0.25: y(t) = \int_0^t d\tau = \tau \Big|_0^t = t, 0 < t < 0.25$

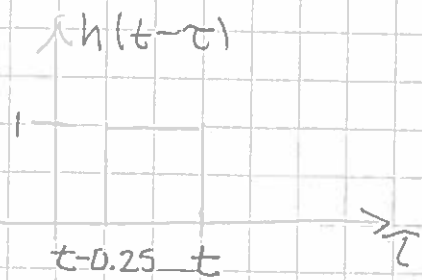
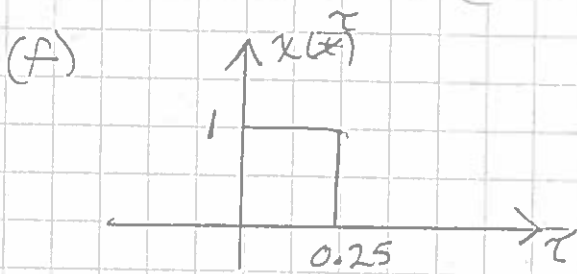
$0.25 < t < 4: y(t) = \int_0^{0.25} d\tau = \tau \Big|_0^{0.25} = 0.25$

$4 < t < 4.25: y(t) = \int_{t-4}^{0.25} d\tau = \tau \Big|_{t-4}^{0.25} = 0.25 - t + 4$

$y(t) = 0, t > 4.25$



PROBLEM 3.5 (Continued)

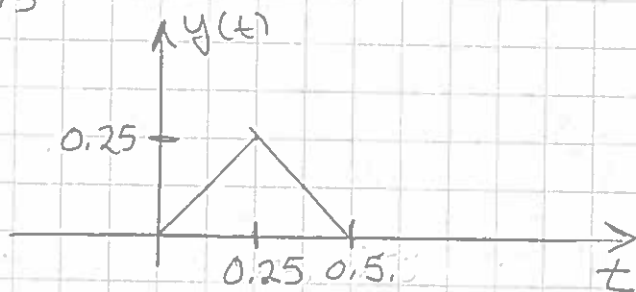


$$y(t) = 0, t < 0$$

$$0 < t < 0.25: y(t) = \int_0^t d\tau = \tau \Big|_0^t = t, 0 < t < 0.25$$

$$0.25 < t < 0.5: y(t) = \int_{t-0.25}^{0.25} d\tau = \tau \Big|_{t-0.25}^{0.25} = 0.5 - t, 0.25 < t < 0.5$$

$$y(t) = 0, t > 0.5$$



Problem 3.6

(a)

$t = 0$:

$$h(\tau)x(-\tau) = 0 \text{ for all } \tau, \text{ so } y(0) = \int_{-\infty}^{\infty} h(\tau)x(-\tau)d\tau = 0.$$

$t = 1$:

$$h(\tau)x(1-\tau) = -2(-2) = 4 \text{ for } 0 \leq \tau < 1$$

and $= 0$ elsewhere.

$$\text{so } y(1) = \int_{-\infty}^{\infty} h(\tau)x(1-\tau)d\tau = \int_0^1 4d\tau = 4.$$

$t = 2$:

$$h(\tau)x(2-\tau) = -2(2) = -4 \text{ for } 0 \leq \tau < 2$$

and $= 0$ elsewhere.

$$\text{so } y(2) = \int_0^2 -4d\tau = -8.$$

$t = 2.667$:

$$h(\tau)x(2.667-\tau) = -2(2) = -4 \text{ for } 0.667 \leq \tau < 1,$$

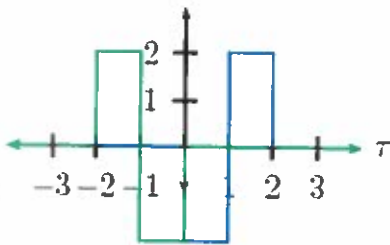
$$= 2(2) = 4 \text{ for } 1 \leq \tau < 1.667,$$

$$= -4 \text{ for } 1.667 \leq \tau < 2,$$

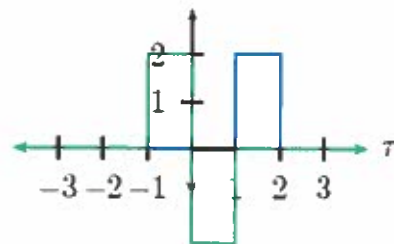
and $= 0$ elsewhere.

$$\text{Therefore } y(2.667) = (-4)(1 - 0.667) + 4(1.667 - 1) - 4(2 - 1.667) = -8(0.333) + 4(0.666) = 0.$$

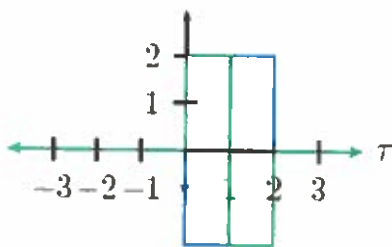
$h(\tau)$ (blue) and $x(-\tau)$ (green)



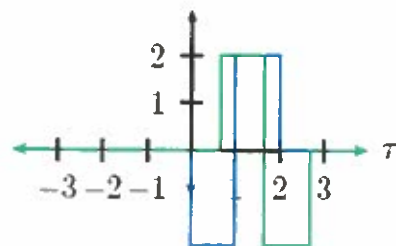
$h(\tau)$ (blue) and $x(1-\tau)$ (green)



$h(\tau)$ (blue) and $x(2-\tau)$ (green)



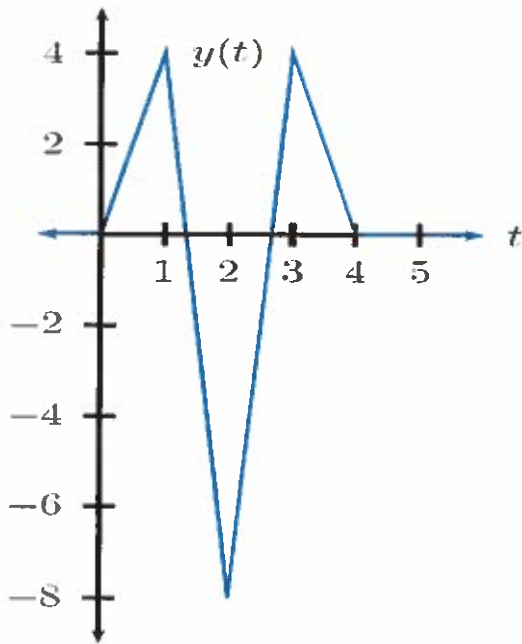
$h(\tau)$ (blue) and $x(2.667-\tau)$ (green)



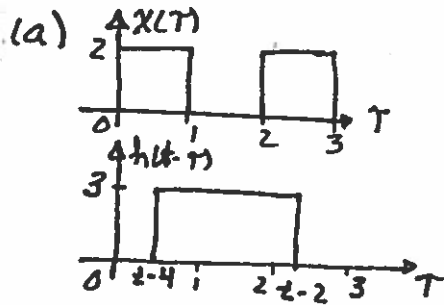
PROBLEM 3.6 (Continued)

(b)

$$\begin{aligned}
 y(t) &= 0, t < 0 \\
 &= \int_0^t -2(-2)d\tau = 4t, 0 \leq t < 1 \\
 &= \int_0^{t-1} 2(-2)d\tau + \int_{t-1}^1 -2(-2)d\tau + \int_1^t -2(2) = -8(t-1) + 4(2-t) = -12t + 16, 1 \leq t < 2 \\
 &= \int_{t-2}^1 2(-2)d\tau + \int_1^{t-1} 2(2)d\tau + \int_{t-1}^2 -2(2)d\tau = 12t - 32, 2 \leq t < 3 \\
 &= \int_{t-2}^2 2(2)d\tau = 4(4-t) = 16 - 4t, 3 \leq t < 4 \\
 &= 0, t \geq 4
 \end{aligned}$$



PROBLEM 3.17



$$4 \leq t \leq 5, y(t) = \int_{t-4}^1 (2)(3) d\tau + \int_2^{t-2} (2)(3) d\tau$$

$$= 6\tau \Big|_{t-4}^1 + 6\tau \Big|_2^{t-2}$$

$$= 6 - 6t + 24 + 6t - 12 - 12 = \underline{6}$$

(b) Maximum output $= \int_0^1 (2)(3) d\tau = 6\tau \Big|_0^1 = \underline{6}$

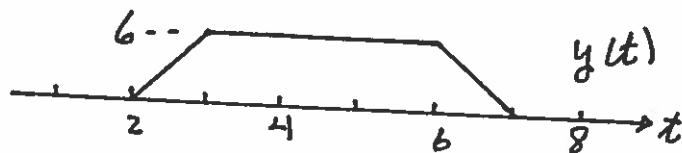
(c) Maximum output occurs $\left\{ \begin{array}{l} \text{from } t-2=1 \Rightarrow t=3 \\ \text{to } t-4=2, t=6 \end{array} \right. \therefore \underline{3 \leq t \leq 6}$

(d) $2 < t < 3, y(t) = \int_0^{t-2} (2)(3) d\tau = 6\tau \Big|_0^{t-2} = \underline{6(t-2)}$

$3 < t < 6, y(t) = \underline{6}$, from (a), (b), and (c),

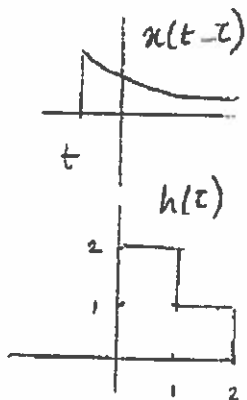
$6 < t < 7, y(t) = \int_{t-4}^3 (2)(3) d\tau = 6\tau \Big|_{t-4}^3 = 18 - 6t + 24 = \underline{42 - 6t}$

$t < 0$ and $t > 7, y(t) = 0$



PROBLEM 3.8

(a) $x(t) = e^t u(-t)$



① $t > 2$ no overlap $\therefore y(t) = 0$
 ② $1 \leq t \leq 2$ $y(t) = \int_0^2 e^{t-\tau} d\tau = e^t \int_0^2 e^{-\tau} d\tau$

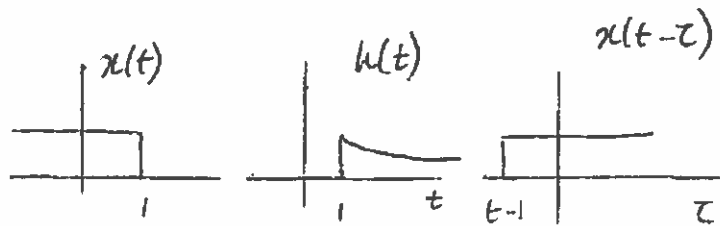
$$y(t) = e^t [e^{-1} - e^{-2}] = 1 - e^{t-2}$$

③ $0 \leq t \leq 1$, $y(t) = 2 \int_0^t e^{t-\tau} d\tau + \int_t^2 e^{t-\tau} d\tau = 2(1 - e^{-t}) + e^t (e^{-1} - e^{-2}) = 2 - e^{t-1} - e^{t-2}$

④ $t < 0$, $y(t) = 2 \int_0^1 e^{t-\tau} d\tau + \int_1^2 e^{t-\tau} d\tau = 2(e^t - e^{t-1}) + e^t (e^{-1} - e^{-2}) = 2e^t - e^{t-1} - e^{t-2}$

$$\therefore y(t) = (1 - e^{t-2}) [u(t-1) - u(t-2)] + (2 - e^{t-1} - e^{t-2}) \times [u(t) - u(t-1)] + (2e^t - e^{t-1} - e^{t-2}) u(-t)$$

(b)



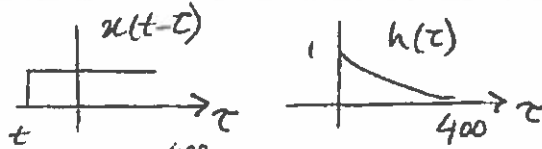
① $t-1 < 1$ or $t < 2$, $y(t) = \int_0^{\infty} e^{-\tau} d\tau = e^{-1}$

② $t-1 > 1$ or $t > 2$ $y(t) = \int_{t-1}^{\infty} e^{-\tau} d\tau = -e^{-\tau} \Big|_{t-1}^{\infty} = e^{-(t-1)}$

$$\therefore y(t) = e^{-1} u(2-t) + e^{-(t-1)} u(t-2)$$

Problem 3.8 (continued)

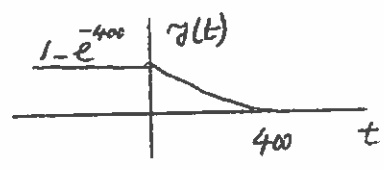
(c) Flip $x(t)$



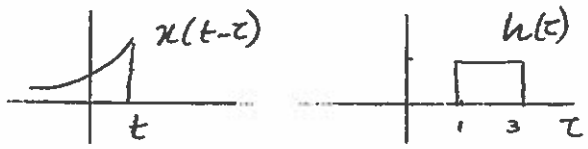
① $t < 0$, $y(t) = \int_t^{400} e^{-z} dz = -e^{-z} \Big|_t^{400} = 1 - e^{-400}$

② $0 < t < 400$, $y(t) = \int_t^{400} e^{-z} dz = e^{-t} - e^{-400}$

③ $t > 400$, $y(t) = 0$



(d)



① $t < 1$, $y(t) = 0$

② $1 \leq t \leq 3$, $y(t) = \int_1^t e^{-(t-z)} dz = e^{-t} \int_1^t e^z dz = e^{-t} (e^t - e) = 1 - e^{-(t-1)}$

③ $t > 3$, $y(t) = \int_1^3 e^{-(t-z)} dz = e^{-t} \int_1^3 e^z dz = e^{-t} (e^3 - e) = e^{-(t-3)} - e^{-(t-1)}$

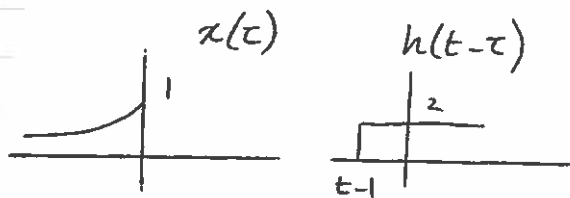
$$\therefore y(t) = (1 - e^{-(t-1)}) [u(t-1) - u(t-3)] + (e^{-(t-3)} - e^{-(t-1)}) u(t-3)$$

PROBLEM 3.8 (continued)

(e)

$$\begin{aligned}
 y(t) &= e^{-at}[u(t) - u(t-2)] * u(t-2) \\
 &= 0, t < 2 \\
 &= \int_0^{t-2} e^{-a\tau} d\tau = \frac{1}{a}(1 - e^{-a(t-2)}), 2 \leq t < 4 \\
 &= \int_0^2 e^{-a\tau} d\tau = \frac{1}{a}(1 - e^{-a^2}), t \geq 4 \\
 &= \frac{1}{a}(1 - e^{-a(t-2)})[u(t-2) - u(t-4)] + \frac{1}{a}(1 - e^{-a^2})u(t-4)
 \end{aligned}$$

(f)



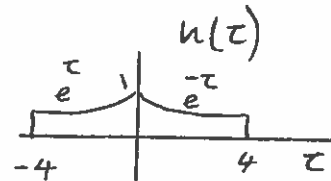
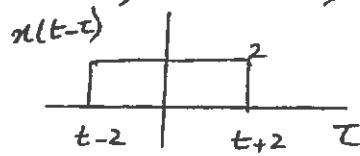
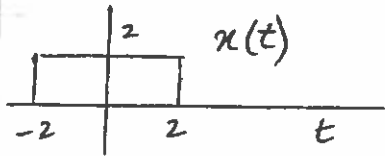
$$\textcircled{1} \quad t-1 < 0 \quad \gamma(t) = \int_{t-1}^0 2e^{\tau} d\tau = 2[1 - e^{t-1}]$$

$$\textcircled{2} \quad t-1 > 0 \quad \gamma(t) = 0$$

$$\therefore \gamma(t) = 2[1 - e^{-(1-t)}]u(1-t)$$

PROBLEM 3.9

$$x_1(t) = 2u(t+2) - 2u(t-2)$$



① $t+2 < -4$, $t < -6$, $y(t) = 0$

② $-4 \leq t+2 \leq 0$, $-6 \leq t \leq -2$

$$y(t) = \int_{-4}^{t+2} 2e^{\tau} d\tau = 2 \left[e^{t+2} - e^{-4} \right]$$

③ $0 \leq t+2 \leq 4$, $-2 \leq t \leq 2$

$$y(t) = 2 \int_{t-2}^0 e^{\tau} d\tau + 2 \int_0^{t+2} e^{-\tau} d\tau = 2 \left[1 - e^{t-2} \right] + 2 \left[1 - e^{-(t+2)} \right]$$

④ $0 \leq t-2 \leq 4$, $2 \leq t \leq 6$

$$y(t) = \int_{t-2}^4 e^{-\tau} d\tau = 2 \left[e^{-(t-2)} - e^{-4} \right]$$

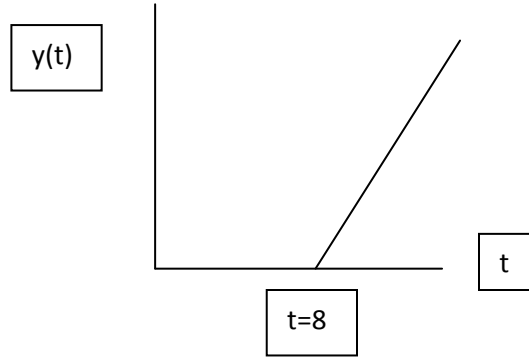
⑤ $t > 6$, $y(t) = 0$

Problem 3.10

$$t < 8, y(t) = 0$$

$$t \geq 8, y(t) = \int_8^t d\tau = (t-8)$$

$$\text{Therefore } y(t) = (t-8)u(t-8)$$



Problem 3.11

$$\begin{aligned} 3.11 \quad \textcircled{a} \quad h(t) &= h_1(t) * h_2(t) = \int_{-\infty}^{\infty} 2e^{-\tau} u(\tau) 2e^{-(t-\tau)} u(t-\tau) d\tau \\ &= 4e^{-t} \int_0^t d\tau = 4te^{-t} u(t) \end{aligned}$$

$$\textcircled{b} \quad h(t) = \delta(t) * \delta(t) = \int_{-\infty}^{\infty} \delta(\tau) \delta(t-\tau) d\tau = \delta(t)$$

$$\textcircled{c} \quad h(t) = 2\delta(t-3) * 2\delta(t-3) = 4\delta(t-6)$$

$$\begin{aligned} \textcircled{d} \quad & (u(t-1) - u(t-5)) * (u(t-1) - u(t-5)) \\ \Rightarrow & \quad 0, \quad t < 2 \\ & \int_1^{t-1} 1(\tau) d\tau = t-2, \quad 2 \leq t < 6 \\ \Rightarrow & \int_{t-5}^5 1(\tau) d\tau = 10-t, \quad 6 \leq t < 10 \\ \Rightarrow & \quad 0, \quad t \geq 10 \\ \Rightarrow & (t-2)[u(t-2) - u(t-6)] \\ & + (10-t)[u(t-6) - u(t-10)] \end{aligned}$$

PROBLEM 3.12

(a) $y_i(t)$ is the output of the i th system

$$y_1(t) = h_1(t) * x(t)$$

$$y_2(t) = h_2(t) * y_1(t) = h_1(t) * h_2(t) * x(t)$$

$$y_3(t) = h_1(t) * h_3(t) * x(t)$$

$$y_5(t) = h_5(t) * x(t)$$

$$y(t) = y_2(t) + y_4(t) = y_2(t) + [y_3(t) + y_5(t)] * h_4(t)$$

$$y(t) = x(t) * \left[h_1(t) * h_2(t) + h_1(t) * h_3(t) * h_4(t) + h_1(t) * h_5(t) \right]$$
$$h(t) = h_1(t) * h_2(t) + h_1(t) * h_3(t) * h_4(t) + h_4(t) * h_5(t)$$

(b) $h(t) = u(t) * 5\delta(t) + u(t) * 5\delta(t) * u(t)$
 $+ u(t) * e^{-2t} u(t)$

now $u(t) * e^{-2t} u(t) = \int_{-\infty}^{\infty} u(\tau) e^{-2(t-\tau)} u(t-\tau) d\tau$

$$= \int_0^t e^{-2(t-\tau)} d\tau = e^{-2t} \int_0^t e^{2\tau} d\tau = \frac{1}{2} (1 - e^{-2t}) u(t)$$

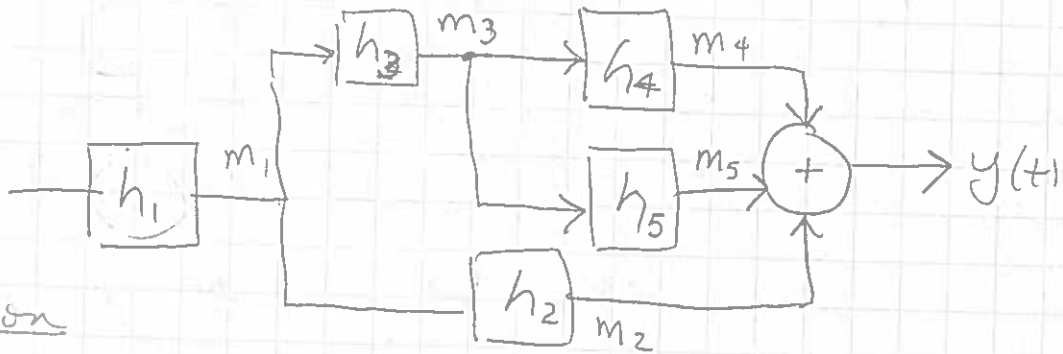
$$\therefore h(t) = 5u(t) + 5t u(t) + \frac{1}{2} (1 - e^{-2t}) u(t)$$

PROBLEM 3.13

$$h_1 = h_3 = 2\delta(t)$$

$$h_2 = h_4 = u(t)$$

$$h_5 = 2u(t)$$



Solution

$$(a) \quad y = m_2 + m_4 + m_5$$

$$m_1 = x * h_1, \quad m_2 = x * h_1 * h_2$$

$$m_3 = m_1 * h_3 = x * h_1 * h_3$$

$$m_4 = m_3 * h_4 = x * h_1 * h_3 * h_4$$

$$m_5 = m_3 * h_5 = x * h_1 * h_3 * h_5$$

$$\therefore y = x * h_1 * h_2 + x * h_1 * h_3 * h_4 + x * h_1 * h_3 * h_5$$

$$y = x * h_1 * [h_2 + h_3 * (h_4 + h_5)] = h(t) * x(t)$$

$$h(t) = h_1(t) * h_2(t) + h_1(t) * h_3(t) * h_4(t) + h_1(t) * h_3(t) * h_5(t)$$

$$(b) \quad \text{impulse response} \Rightarrow x(t) = \delta(t), \quad y(t) = h(t)$$

$$h(t) = \delta(t) * 2\delta(t) * [u(t) + 2\delta(t) * (u(t) + 2u(t))]$$

$$= \delta(t) * 2\delta(t) * [u(t) + 2\delta(t) * 3u(t)]$$

$$h(t) = 2\delta(t) * [u(t) + 6u(t)]$$

$$= 2u(t) + 12u(t)$$

$$h(t) = 14u(t)$$

PROBLEM 3.13 (continued)

- (c) BLOCK 1 = BLOCK 3 = amplifier with gain=2
BLOCK 2 = BLOCK 4 = unity-gain integrator
BLOCK 5 = integrating amplifier with gain=2

(d) $m_1 = 2\delta(t)$, $m_2 = 2\delta(t) * u(t) = 2u(t)$
 $m_3 = 2\delta(t) * 2\delta(t) = 4\delta(t)$
 $m_4 = 4\delta(t) * u(t) = 4u(t)$
 $m_5 = 4\delta(t) * 2u(t) = 8u(t)$
 $h(t) = m_2 + m_4 + m_5 = 14u(t)$

(e) $\delta(t)h(t) = 14u(t) \checkmark$

PROBLEM 3.14

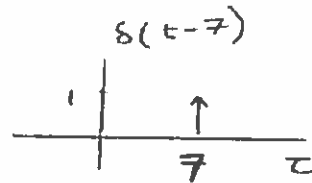
a) $x(t) = \delta(t) \rightarrow y(t) = h(t)$

$y(t) = x(t-7)$

$h(t) = \delta(t-7)$

b) $y(t) = \int_{-\infty}^t x(\tau-7) d\tau$

$h(t) = \int_{-\infty}^t \delta(\tau-7) d\tau$



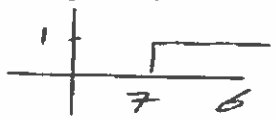
$t < 7, h(t) = 0$

$t > 7, h(t) = 1$

$\therefore h(t) = u(t-7)$

c) $y(t) = \int_{-\infty}^t \left[\int_{-\infty}^b x(\tau-7) d\tau \right] db$ let $x(t) = \delta(t)$

$h(t) = \int_{-\infty}^t \left[\int_{-\infty}^b \delta(\tau-7) d\tau \right] db = \int_{-\infty}^t u(b-7) db$



$t < 7, h(t) = 0$

$t > 7, h(t) = \int_7^t db = (t-7)$

$\therefore h(t) = (t-7) u(t-7)$

PROBLEM 3.15

$$\text{let } x(t-\tau) = \begin{cases} 1 & h(\tau) > 0 \\ -1 & h(\tau) < 0 \end{cases} \therefore x \text{ is bounded}$$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau$$

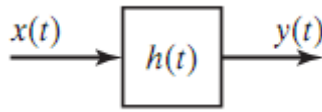
$$h(\tau) x(t-\tau) = \begin{cases} h(\tau), & h(\tau) > 0 \\ -h(\tau), & h(\tau) < 0 \end{cases}$$

$$\therefore h(\tau) x(t-\tau) = |h(\tau)|$$

$$\therefore y(t) = \int_{-\infty}^{\infty} |h(\tau)| d\tau \quad \text{which is assumed unbounded}$$

\therefore System is not BIBO stable

Problem 3.16 .



a) $x(t)=\delta(t),y(t)=h(t)$, so $y(t)=x(t-9),h(t)=\delta(t-9)$

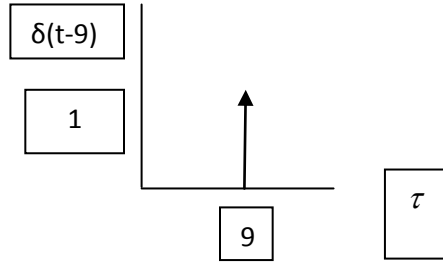
b) $y(t) = \int_{-\infty}^t x(\tau - 9) d\tau,$

$h(t) = \int_{-\infty}^t \delta(\tau - 9) d\tau,$

if $t < 9, h(t) = 0$

if $t > 9, h(t) = 1$

Therefore $h(t) = u(t-9)$



c) $y(t) = \int_{-\infty}^t \left[\int_{-\infty}^{\sigma} x(\tau - 9) d\tau \right] d\sigma$ let $x(t) = \delta(t)$

$h(t) = \int_{-\infty}^t \left[\int_{-\infty}^{\sigma} x(\tau - 9) d\tau \right] d\sigma = \int_{-\infty}^{\sigma} u(\tau - 9) d\tau$

$t < 9, \quad h(t) = 0$

$t > 9, \quad h(t) = \int_9^t d\sigma = (t - 9)$

Therefore $h(t) = (t-9)u(t-9)$

d) $x(t)=\delta(t),y(t)=h(t)$, so $y(t)=x(t+9),h(t)=\delta(t+9)$

Problem 3.17 Linear

a) Not time invariant

b) $\delta(t)=\sin(4t)\delta(t)=1 \quad \delta(t)=\delta(t)$

c) $\delta(t-\pi/2)=\sin 4t \quad \delta(t-\pi/2)=\sin(\pi/2) \quad \delta(t-\pi/2)=1 \quad \delta(t)=1$

Problem 3.18

- a) Stable,casual
- b) Not Stable,casual
- c) Stable, not casual
- d) Not Stable, not casual
- e) Stable, not casual
- f) Stable, casual
- g) Stable, casual
- h) Stable, casual

PROBLEM 3.19

$$y(t) = \int_{-\infty}^t e^{-(t-\tau)} x(\tau) d\tau$$

$$(a) h(t) = \int_{-\infty}^t e^{-(t-\tau)} s(\tau) d\tau = \begin{cases} e^{-t}, & t \geq 0 \\ 0, & t < 0 \end{cases} = \underline{e^{-t} u(t)}$$

$$(b) \underline{y(t)}, h(t) = 0, t < 0$$

$$(c) y(t) = \int_{-\infty}^t e^{-(t-\tau)} u(\tau+1) d\tau = \int_{-1}^t e^{-t} e^{\tau} d\tau \\ = e^{-t} (e^{\tau} \Big|_{-1}^t) = e^{-t} (e^t - e^{-1}) u(t+1) \\ = \underline{[1 - e^{-(t+1)}] u(t+1)}$$

$$(d) y(t) = h(t) * s(t) - h(t) * s(t-1) * s(t) \\ = h(t) * s(t) - h(t-1) * s(t) = h(t) - h(t-1) \\ = \underline{e^{-t} u(t) - e^{-(t-1)} u(t-1)}$$

$$(e) (i) y(t) = y_c(t) - y_c(t) \Big|_{t+1 \leftarrow t} \\ = \underline{[1 - e^{-(t+1)}] u(t+1) - [1 - e^{-t}] u(t)}$$

$$(ii) y(t) = h(t) * u(t+1) = \int_{-\infty}^{\infty} u(t-\tau+1) [e^{-\tau} u(\tau) - e^{-(\tau-1)} u(\tau-1)] d\tau \\ = \int_0^{\infty} e^{-\tau} u(t+1-\tau) d\tau - e^{-1} \int_1^{\infty} e^{-\tau} u(t+1-\tau) d\tau = I_1 - I_2 \\ I_1 = \int_0^{t+1} e^{-\tau} d\tau = -e^{-\tau} \Big|_0^{t+1} = [1 - e^{-(t+1)}] u(t+1) \\ I_2 = e^{-1} \int_1^{t+1} e^{-\tau} d\tau = e^{-1} (-e^{-\tau}) \Big|_1^{t+1} = e^{-1} (e^{-1} - e^{-(t+1)}) u(t) \\ = (1 - e^{-t}) u(t)$$

$$\therefore y(t) = \underline{[1 - e^{-(t+1)}] u(t+1) - [1 - e^{-t}] u(t)}$$

3.20.

3.20

$$(a) \quad y(t) = \int_{-\infty}^t e^{-4(t-\tau)} x(\tau-1) d\tau$$

$$(i) \quad h(t) = \int_{-\infty}^t e^{-4(t-\tau)} \delta(\tau-1) d\tau$$

$$= e^{-4(t-1)} u(t-1)$$

(ii) $h(t) = 0$ for $t < 0$ \therefore causal

$$(iii) \quad \int_{-\infty}^{\infty} |e^{-4(t-1)} u(t-1)| dt = \int_1^{\infty} e^{-4(t-1)} dt$$

$$= e^4 \left(\frac{e^{-4t}}{-4} \right) \Big|_1^{\infty} = e^4 \left(\frac{e^{-4}}{4} \right) = 1/4$$

= stable

$$(b) (i) \quad y(t) = \int_{-\infty}^t e^{-4(t+\tau)} x(\tau+1) d\tau$$

$$(i) \quad h(t) = \int_{-\infty}^t e^{-4(t+\tau)} \delta(\tau+1) d\tau = e^{-4(t+1)} u(t+1)$$

(ii) $h(t) \neq 0$ for $t < 0$ \therefore non causal

$$(iii) \quad \int_{-\infty}^{\infty} |e^{-4(t+1)} u(t+1)| dt = \int_{-1}^{\infty} e^{-4(t+1)} dt$$

$$= e^4 \left(\frac{e^{-4t}}{-4} \right) \Big|_{-1}^{\infty} = \frac{e^8}{4} = \text{stable}$$

3.20

$$(c) \quad y(t) = \int_{-\infty}^{\infty} e^{-2(t-\tau)} x(\tau-1) d\tau$$

$$(i) \quad h(t) = \int_{-\infty}^{\infty} e^{-2(t-\tau)} \delta(\tau-1) d\tau = e^{-2(t-1)}$$

(ii) $h(t) \neq 0, t < 0 \therefore$ non casual

$$(iii) \quad \int_{-\infty}^{\infty} |e^{-2(t-1)}| dt = \int_{-\infty}^{\infty} e^{-2t} e^2 dt$$

$$= e^2 \left(\frac{e^{-2t}}{-2} \right) \Big|_{-\infty}^{\infty}$$

unbounded \therefore unstable

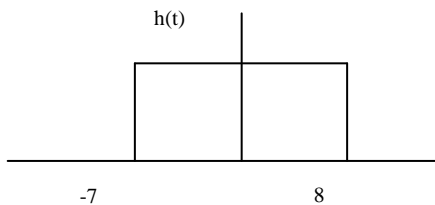
Problem 3.21

a) Not casual

b) Stable

$$c) \quad x(t) = \delta(t-2) - 2\delta(t+2)$$

$$y(t) = x(t) * h(t) = h(t-2) - 2h(t+2)$$



Problem 3.22

(a) Non casual

(b) Stable

(c)

$$y(t) = h(t) * \delta(t-3) - 2h(t) * \delta(t-5) = h(t-3) - 2h(t-5)$$

$$= [u(t-3) - 2u(t+1) + u(t-5)] - 2[u(t-5) - 2u(t-1) + u(t-7)]$$

Problem 3.23.

(a) $(t-1-2)u(t-1-2) = (t-3)u(t-3)$

(b) $x(t)=1$ if $t>1$, $h(t) =1$ if $t>2$

Problem 3.24

a) Casual since $h(t)=0$ when $t<0$

b) Stable

c) Not casual and not stable

PROBLEM 3.25

(i) Characteristic equation: $s + 3 = 0$, solution $s = -3$

$$\Rightarrow y_c(t) = Ce^{-3t}u(t)$$

Forced response of the form: $y_p(t) = Pu(t)$ where $\frac{dy_p(t)}{dt} + 3y_p(t) = 3u(t)$

$$\Rightarrow 0 + 3Pu(t) = 3u(t) \Rightarrow P = 1$$

$$y(t) = y_c(t) + y_p(t) = (Ce^{-3t} + 1)u(t)$$

$$\text{Need } y(0) = C + 1 = -1 \Rightarrow C = -2$$

$$\Rightarrow y(t) = (-2e^{-3t} + 1)u(t)$$

This clearly satisfies the differential equation and initial conditions because

$$\frac{dy(t)}{dt} + 3y(t) = 6e^{-3t} + 3(-2e^{-3t} + 1) = 3, t > 0$$

$$y(0) = -2e^{-3 \cdot 0} + 1 = -1$$

(ii) Characteristic equation: $s + 3 = 0$, solution $s = -3$

$$\Rightarrow y_c(t) = Ce^{-3t}u(t)$$

Forced response of the form $y_p(t) = Pe^{-2t}u(t)$ where $\frac{dy_p(t)}{dt} + 3y_p(t) = 3e^{-2t}u(t)$

$$\Rightarrow (-2P + 3P)e^{-2t}u(t) = 3e^{-2t}u(t) \Rightarrow P = 3$$

$$y(t) = y_c(t) + y_p(t) = (Ce^{-3t} + 3e^{-2t})u(t)$$

$$\text{Need } y(0) = C + 3 = 2 \Rightarrow C = -1$$

$$\Rightarrow y(t) = (3e^{-2t} - e^{-3t})u(t)$$

This clearly satisfies the differential equation and initial conditions since

$$\frac{dy(t)}{dt} + 3y(t) = (-6e^{-2t} + 3e^{-3t}) + 3(3e^{-2t} - e^{-3t}) = 3e^{-2t}, t > 0$$

$$y(0) = 3e^{-2 \cdot 0} - e^{-3 \cdot 0} = 2$$

(iii) Characteristic equation: $s + 10 = 0$

$$\Rightarrow y_c(t) = Ce^{-10t}$$

$$y_p(t) = Pe^{-t} \Rightarrow -Pe^{-t} + 10e^{-t} = e^{-t} \Rightarrow P = \frac{1}{9}$$

$$y(t) = \frac{1}{9}e^{-t} + Ce^{-10t}, t \geq 0$$

$$y(0) = \frac{1}{9} + C = 2 \Rightarrow C = 2 - \frac{1}{9} = \frac{17}{9}$$

$$\therefore y(t) = \frac{1}{9}e^{-t} + \frac{17}{9}e^{-10t} \Rightarrow y(0) = 2 \checkmark$$

$$\frac{dy(t)}{dt} = -\frac{1}{9}e^{-t} - \frac{170}{9}e^{-10t}$$

$$\therefore -\frac{1}{9}e^{-t} - \frac{170}{9}e^{-10t} + \frac{10}{9}e^{-t} + \frac{170}{9}e^{-10t} = e^{-t} \checkmark$$

PROBLEM 3.25 (continued)

(iv) Characteristic equation: $s^2 + 6s + 5 = 0$
 $(s+5)(s+1) = 0 \Rightarrow y_c(t) = C_1 e^{-t} + C_2 e^{-5t}$

$$y_p(t) = P \Rightarrow 0 + 6(0) + 5P = 10 \Rightarrow \underline{P=2}$$

$$\therefore y(t) = 2 + C_1 e^{-t} + C_2 e^{-5t}$$

$$y(0) = 2 + C_1 + C_2 = -1 \Rightarrow C_1 + C_2 = -3$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = -C_1 - 5C_2 = 0 \Rightarrow C_1 = -5C_2$$

$$-5C_2 + C_2 = -3 \Rightarrow C_2 = \frac{3}{4} \quad C_1 = -\frac{15}{4}$$

$$y(t) = 2 - \frac{15}{4} e^{-t} + \frac{3}{4} e^{-5t}$$

$$y(0) = 2 - \frac{15}{4} + \frac{3}{4} = -1 \quad \checkmark$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = \frac{15}{4} e^{-t} - \frac{15}{4} e^{-5t} \Rightarrow \left. \frac{dy(t)}{dt} \right|_{t=0} = 0 \quad \checkmark$$

(v) Characteristic equation: $-0.7s + 1 = 0 \Rightarrow s - \frac{1}{0.7} = 0$, solution $s = \frac{1}{0.7} = 10/7$

$$\Rightarrow y_c(t) = C e^{t/0.7} u(t)$$

Forced response of the form $y_p(t) = P e^{3t} u(t)$ where $\frac{dy_p(t)}{dt} - \frac{10}{7} y_p(t) = \frac{-30}{7} e^{3t} u(t)$

$$\Rightarrow 3P - \frac{10}{7} P = \frac{-30}{7}$$

Solving for P gives $P = -\frac{30}{11}$

$$y(t) = y_c(t) + y_p(t) = (C e^{t/0.7} - (\frac{30}{11}) e^{3t}) u(t)$$

Need $y(0) = C - \frac{30}{11} = -1 \Rightarrow C = \frac{19}{11}$

$$\Rightarrow y(t) = (\frac{19}{11} e^{t/0.7} - \frac{30}{11} e^{3t}) u(t)$$

This clearly satisfies the differential equation and initial conditions since

$$\frac{dy(t)}{dt} - \frac{1}{0.7} y(t) = 2.47 e^{t/0.7} - 3(\frac{30}{11}) e^{3t} - 2.47 e^{t/0.7} + \frac{300}{11} e^{3t} = \frac{-30}{7} e^{3t}$$

$$y(0) = \frac{19}{11} - \frac{30}{11} = -1$$

PROBLEM 3.25 (continued)

(vi) Characteristic equation: $-10s + 10s = 0$

$$\Rightarrow s = 1$$

$$y_c(t) = C_1 e^t, \quad y_p(t) = P_1 \cos(t) + P_2 \sin(t)$$

$$+10[P_1 \sin(t) - P_2 \cos(t)] + 10[P_1 \cos(t) + P_2 \sin(t)]$$

$$= 20 \cos t, \quad t \geq 0$$

$$\Rightarrow 10P_1 + 10P_2 = 0 \Rightarrow P_1 + P_2 = 0$$

$$-10P_2 + 10P_1 = 20 \Rightarrow P_1 - P_2 = 2$$

$$\Rightarrow \underline{P_1 = 1, P_2 = -1}$$

$$\therefore y(t) = C_1 e^t + \cos(t) - \sin(t)$$

$$y(0) = C_1 + 1 = -10 \Rightarrow C_1 = -11$$

$$y(t) = -11e^t + \cos t - \sin t \Rightarrow \underline{y(0) = -10} \checkmark$$

$$\frac{dy(t)}{dt} = -11e^t - \sin(t) - \cos(t)$$

$$\therefore \cancel{-11e^t} + 10\sin(t) + 10\cos(t) + \cancel{11e^t} + 10\cos(t) - 10\sin(t) = 20\cos(t), \quad t \geq 0 \quad \checkmark$$

(vii) Characteristic Equation: $s^2 + s + 2 = 0 \Rightarrow s_{1,2} = \frac{-1 \pm j\sqrt{7}}{2}$

$$y_c(t) = C_1 e^{-\frac{1}{2} j\sqrt{7}t} + C_2 e^{-\frac{1}{2} - j\frac{\sqrt{7}}{2}t}$$

$$y_p(t) = P \Rightarrow 2P = 3 \Rightarrow \underline{P = 3/2}$$

$$y(t) = \frac{3}{2} + C_1 e^{-(1-j\sqrt{7})t/2} + C_2 e^{-(1+j\sqrt{7})t/2}$$

$$y(0) = \frac{3}{2} + C_1 + C_2 = 2 \Rightarrow \underline{C_1 + C_2 = \frac{1}{2}}$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = -\frac{1}{2}(1-j\sqrt{7})C_1 - \frac{1}{2}(1+j\sqrt{7})C_2 = 1$$

$$+\frac{1}{2}(1-j\sqrt{7})C_1 + \frac{1}{2}(1+j\sqrt{7})C_2 = +\frac{1}{4}(1-j\sqrt{7})$$

$$-j\sqrt{7}C_2 = \frac{5}{4} - j\frac{\sqrt{7}}{4}$$

$$\underline{C_2 = \frac{1}{4} + j\frac{5}{4\sqrt{7}}} \Rightarrow C_1 = \frac{1}{2} - C_2 = \frac{1}{4} - j\frac{5}{4\sqrt{7}}$$

PROBLEM 3.25 (vii) (continued)

$$y(t) = \frac{3}{2} + \left(\frac{1}{4} - j\frac{5}{4\sqrt{7}}\right)e^{-\frac{1}{2}(1-j\sqrt{7})t} + \left(\frac{1}{4} + j\frac{5}{4\sqrt{7}}\right)e^{-\frac{1}{2}(1+j\sqrt{7})t}$$

$$y(0) = \frac{3}{2} + \frac{1}{4} - j\frac{5}{4\sqrt{7}} + \frac{1}{4} + j\frac{5}{4\sqrt{7}} = 2 \quad \checkmark$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = \left(\frac{1}{4} - j\frac{5}{4\sqrt{7}}\right)\left(-\frac{1}{2} + j\frac{\sqrt{7}}{2}\right) + \left(\frac{1}{4} + j\frac{5}{4\sqrt{7}}\right)\left(-\frac{1}{2} - j\frac{\sqrt{7}}{2}\right)$$

$$= -\frac{1}{8} + j\frac{\sqrt{7}}{8} + j\frac{5}{8\sqrt{7}} + \frac{5}{8} - \frac{1}{8} - j\frac{\sqrt{7}}{8} - j\frac{5}{8\sqrt{7}} + \frac{5}{8} = 1 \quad \checkmark$$

PROBLEM 3.26

$$y(t) = h_1(t) * [x(t) - h_2(t) * y(t)]$$
$$= h_1(t) * x(t) - h_1(t) * h_2(t) * y(t)$$

$$h_1(t) = 2u(t), \quad h_2(t) = \frac{1}{2}\delta(t)$$

$$y(t) = x(t) * 2u(t) - \frac{1}{2}\delta(t) * 2u(t) * y(t)$$

$$\frac{1}{2}\delta(t) * 2u(t) = u(t)$$

$$\therefore y(t) = x(t) * 2u(t) - y(t) * u(t)$$

$$= 2 \int_{-\infty}^{\infty} x(\tau) u(t-\tau) d\tau - \int_{-\infty}^{\infty} y(\tau) u(t-\tau) d\tau$$

$$y(t) = 2 \int_{-\infty}^t x(\tau) d\tau - \int_{-\infty}^t y(\tau) d\tau$$

$$\frac{dy(t)}{dt} = 2x(t) - y(t)$$

$$\Rightarrow \boxed{\frac{dy(t)}{dt} + y(t) = 2x(t)}$$

PROBLEM 3.27

(a) characteristic equation is $s^2 - 2.5s + 1 = (s - 2)(s - 0.5) = 0$; roots are $s = 2, 0.5$;
modes are $e^{2t}, e^{0.5t}$. Unstable since roots > 0 , and real.

(b) characteristic equation $s^2 + 9 = (s - 3j)(s + 3j) = 0$, roots $s = 3j, -3j$;
modes e^{3jt}, e^{-3jt} . Unstable since real part of roots is 0 (roots lie on imaginary axis).

(c) characteristic equation: $S^2 + 3.5S - 2 = 0$
roots are $S_1 = -4, S_2 = 0.5$
modes are $e^{-4t}, e^{0.5t}$
unstable, $\lim_{t \rightarrow \infty} e^{0.5t} \rightarrow \infty$

(d) characteristic equation: $S^3 + 5S^2 + 4S + 3 = 0$
roots are $S_1 = -4.22, S_2 = -0.3897 + j0.7476, S_3 = -0.3897 - j0.7476$
modes: $e^{-4.22t}, e^{(-0.3897 + j0.7476)t}, e^{(-0.3897 - j0.7476)t}$
stable since all roots have negative real parts.

(e) characteristic equation: $S^3 + 2S^2 + 4S + 8 = 0$
roots: $-2, +j2, -j2$
modes: $e^{-2t}, e^{j2t}, e^{-j2t}$
Not stable, 2 roots do not have negative real parts.

(f) characteristic equation: $S^3 + 2S^2 + 4S + 16 = 0$
roots: $-2.7064, 0.3532 + j2.4056, 0.3532 - j2.4056$
modes: $e^{-2.7064t}, e^{(0.3532 + j2.4056)t}, e^{(0.3532 - j2.4056)t}$
Unstable - 2 roots have positive real parts.

PROBLEM 3.28

(a) Stable. All characteristic roots have negative real parts.

(b) Characteristic equation: $s^2 + 1.5s - 1 = 0$
roots: $s_1 = -2$, $s_2 = +0.5$

unstable, 1 root is positive and real.

(c) Characteristic equation: $s^2 + 2s = 0$
roots: $s = 0$, $s = -2$

unstable: one root has non-negative real part.

(d) Characteristic equation: $s^3 + 2s^2 + 8s + 32 = 0$
roots: -2.9559 , $0.4780 + j3.2553$, $0.4780 - j3.2553$

unstable: 2 roots have positive real parts.

(e) Characteristic equation: $s^3 + 2s^2 + 8s + 16 = 0$
roots: -2 , $j2.8284$, $-j2.8284$

unstable, 2 roots have non-negative real parts.

(f) Characteristic equation: $s^2 + 2s^2 + 8s + 8 = 0$
roots: -2 , $j2$, $-j2$

unstable. 2 roots have non-negative real parts

PROBLEM 3.29

(a) (i) From solution to Problem 3.25, $s = -3$.
 \therefore mode is e^{-3t} .

(ii) mode is e^{-3t} ,

(iii) $s = -10$, \therefore mode is e^{-10t}

(iv) $s_1 = -1$, $s_2 = -5$, \therefore modes are e^{-t} , e^{-5t}

(v) $s = \frac{10}{7}$, mode is $e^{10/7 t}$

(b) $e^{-at} = e^{-t/\tau} \Rightarrow \tau = \frac{1}{a} = \text{time constant}$.

(i) $e^{-3t} = e^{-t/\tau} \Rightarrow \tau = 1/3 \text{ (s)}$.

(ii) $e^{-3} = e^{-t/\tau} \Rightarrow \tau = 1/3 \text{ (s)}$.

(iii) $e^{-10t} = e^{-t/\tau} \Rightarrow \tau = 1/10 \text{ (s)}$

(iv) $e^{-5t} = e^{-t/\tau} \Rightarrow \tau_2 = 1/5 \text{ (s)}$

$e^{-t} = e^{-t/\tau} \Rightarrow \tau_1 = 1 \text{ (s)}$

(v) $e^{+10/7 t} = e^{-t/\tau} \Rightarrow \tau = -\frac{7}{10} \text{ (s)} \leftarrow \text{unstable mode}$

(c) The natural response of a stable system reaches steady-state in approximately four time constants
 $T_s \approx 4\tau$

(i) $\tau = 1/3 \text{ (s)} \Rightarrow T_s \approx 4/3 \text{ (s)}$

(ii) $T_s \approx 4/3 \text{ (s)}$

(iii) $\tau = 1/10 \text{ (s)} \Rightarrow T_s \approx 4/10 \text{ (s)}$

(iv) $\tau_1 = 1 \text{ (s)}$, $\tau_2 = 1/5 \text{ (s)}$ $T_s \approx 4\tau_1 = 4 \text{ (s)}$

(v) The system unstable - it will not reach steady-state.

(d) Char. eqn: $s^2 + 9 = 0 \Rightarrow s_1 = j3$, $s_2 = -j3$
Modes: e^{j3t} , e^{-j3t}

the real part of each root is zero, therefore the time constant is undefined. The natural response is oscillatory.

PROBLEM 3.30

(a) Characteristic equation: $0.01s^2 + 1 = 0$
 $s^2 + 100 = 0 \Rightarrow s_1 = j10, s_2 = -j10$

modes: e^{j10t}, e^{-j10t}

(b) $y_c(t) = C e^{j\theta} e^{j10t} + C e^{-j\theta} e^{-j10t}$
 $= 2C \left[\frac{e^{j(10t+\theta)} + e^{-j(10t+\theta)}}{2} \right]$

From Euler's relation: $\cos(\phi) = \frac{e^{j\phi} + e^{-j\phi}}{2}$

$y_c(t) = 2C \cos(10t + \theta)$

(c) The differential equation of the system is

$$\frac{d^2 y(t)}{dt^2} + 100y(t) = 100x(t), \quad x(t) = e^{-t}u(t)$$

$$y_p(t) = P e^{-t}$$

$$P e^{-t} + 100P e^{-t} = 100 e^{-t}, \quad t \geq 0$$

$$P = \frac{100}{101}$$

$$y(t) = \frac{100}{101} e^{-t} + 2C \cos(10t + \theta)$$

$$y(0) = 0 = \frac{100}{101} + 2C \cos \theta$$

$$\Rightarrow C \cos \theta = -\frac{50}{101}$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = -\frac{100}{101} - 20C \sin \theta = 0$$

$$\Rightarrow C \sin \theta = -\frac{5}{101}$$

$$\frac{C \sin \theta}{C \cos \theta} = \tan \theta = 0.1 \Rightarrow \theta = \tan^{-1}(0.1) = 5.71 \text{ (rad)}$$

$$\cos \theta = 0.995, \quad \sin \theta = 0.0995$$

$$C = \frac{-50}{101} \cdot \frac{1}{0.995} = -0.4975$$

$$y(t) = \frac{100}{101} e^{-t} - 0.9951 \cos(10t + 327.16^\circ)$$

PROBLEM 3.30 (Continued)

$$(d) \quad y(0) = \frac{100}{101} + 0.9951 \cos(327.16^\circ) \approx 0 \quad \checkmark$$

$$\left. \frac{dy(t)}{dt} \right|_{t=0} = -\frac{100}{101} + 0.9951(10) \sin(327.16^\circ) \approx 0 \quad \checkmark$$

PROBLEM 3.31

$$(a) \quad x(t) = 3u(t) = 3e^{0t} \Rightarrow s=0$$

$$(i) \quad H(0) = \frac{10}{4} = 2.5$$

$$y_{ss}(t) = H(0)x(t) = (3)(2.5) = \underline{7.5}$$

$$(ii) \quad H(0) = \frac{5}{10} = 0.5 \Rightarrow y_{ss}(t) = (0.5)(3) = \underline{1.5}$$

$$(b) \quad x(t) = 3e^{4t}u(t) \Rightarrow s=4$$

$$(i) \quad H(4) = \frac{10}{4+4} = 1.25$$

$$y_{ss}(t) = H(4)x(t) = (1.25)(3e^{4t}) = \underline{3.75e^{4t}}$$

$$(ii) \quad H(4) = \frac{2(4)+5}{4^2+2(4)+10} = \frac{13}{34} \Rightarrow y_{ss}(t) = \underline{\frac{39}{34}e^{4t}}$$

$$(c) \quad x(t) = 3 \cos 4t, \Rightarrow s_{1,2} = \pm j4$$

$$(i) \quad H(j4) = \frac{10}{j4+4} = 1.768 \angle -45^\circ$$

$$y_{ss}(t) = H(j4)x(t) = (1.768)(3) \cos(4t - 45^\circ) \\ = \underline{5.303 \cos(4t - 45^\circ)}$$

$$(ii) \quad H(j4) = \frac{5+j8}{-16+j8+10} = \frac{5+j8}{-6+j8} = 0.943 \angle -68.9^\circ$$

$$y(t) = (0.943)(3) \cos(4t - 68.9^\circ) = \underline{2.83 \cos(4t - 68.9^\circ)}$$

PROBLEM B.31 (Continued)

(d) $x(t) = 3e^{j4t} \Rightarrow s = j4 \therefore$ solution is the same as given for (c).

(e) $x(t) = 3 \sin 4t = 3 \cos(4t - 90^\circ)$
 $\Rightarrow s = j4$

(i) $H(j4) = 1.768 \angle -45^\circ \sim$ from (c)(i)
 $\Rightarrow y(t) = 5.303 \cos(4t - 90^\circ - 45^\circ)$
 $y(t) = 5.303 \sin(4t - 45^\circ)$

(ii) $H(j4) = 0.943 \angle -68.9^\circ \sim$ from (c)
 $\Rightarrow y(t) = 2.83 \cos(4t - 90^\circ - 68.9^\circ)$
 $y(t) = 2.83 \sin(4t - 68.9^\circ)$

(f) $x(t)$ of (e) is that of (c) delayed by 90° .
 $\therefore y(t)$ of (e) is that of (c) delayed by 90° .

(g) (i) Char. eqn: $s+4=0 \Rightarrow s=-4$
mode: $e^{-4t} = e^{-t/\tau} \Rightarrow \tau = \frac{1}{4} \text{ (s)}$.

(ii) Char. eqn: $s^2 + 2s + 10 \Rightarrow s_{1,2} = -1 \pm j\sqrt{24}$
modes: $e^{-t + j\sqrt{24}t}, e^{-t - j\sqrt{24}t}$
 $e^{-t} = e^{-t/\tau} \Rightarrow \tau = 1 \text{ (s)}$

(iii) for the system of (a)(i) $T_s \approx 4\tau \approx 1 \text{ (s)}$

for the system of (a)(ii) $T_s \approx 4\tau = 4 \text{ (s)}$

PROBLEM 3.32

$$x(t) = 2 \cos 4t \Rightarrow s = j4$$

$$(a) H(j4) = \frac{k}{j4+a}, \quad H(j4)x(t) = 5 \cos(4t - 45^\circ)$$

$$\Rightarrow H(j4) = \frac{5}{2} \angle -45^\circ = \frac{k}{\sqrt{4^2+a^2}} \angle -\tan^{-1}\left(\frac{4}{a}\right)$$

$$\therefore \frac{k}{\sqrt{4^2+a^2}} = \frac{5}{2} \quad \text{and} \quad a = 4.$$

$$k = (\sqrt{4^2+4^2}) \left(\frac{5}{2}\right) = \underline{14.142}$$

$$(b) \begin{aligned} &>> n = [0 \ 14.142]; \quad d = [1 \ 4]; \\ &>> h = \text{polyval}(n, 4*j) / \text{polyval}(d, 4*j); \\ &>> y_{\text{mag}} = 2 * \text{abs}(h); \\ &>> y_{\text{phase}} = \text{angle}(h) * 180 / \pi \end{aligned}$$

$$(c) x(t) = 2 \cos 3t \Rightarrow s = j3$$

$$H(j3) = \frac{k}{j3+a}; \quad H(j3)x(t) = 2.222 \cos(3t - 56.31^\circ)$$

$$\Rightarrow H(j4) = \frac{2.222}{2} \angle -56.31^\circ = \frac{k}{\sqrt{3^2+a^2}} \angle -\tan^{-1}\left(\frac{3}{a}\right)$$

$$\therefore \tan^{-1}\left(\frac{3}{a}\right) = 56.31^\circ \Rightarrow a = \frac{3}{\tan(56.31^\circ)} = 2$$

$$\frac{k}{\sqrt{3^2+2^2}} = 1.111 \Rightarrow k = 1.111 \sqrt{13} \approx 4$$

$$H(s) = \frac{4}{s+2}$$

3.33.

3.33

(a)

(b)

$$\frac{d^2 y}{dt^2} = 2 \frac{d^2 x}{dt^2} + \frac{dx}{dt} + 3y$$

3.33

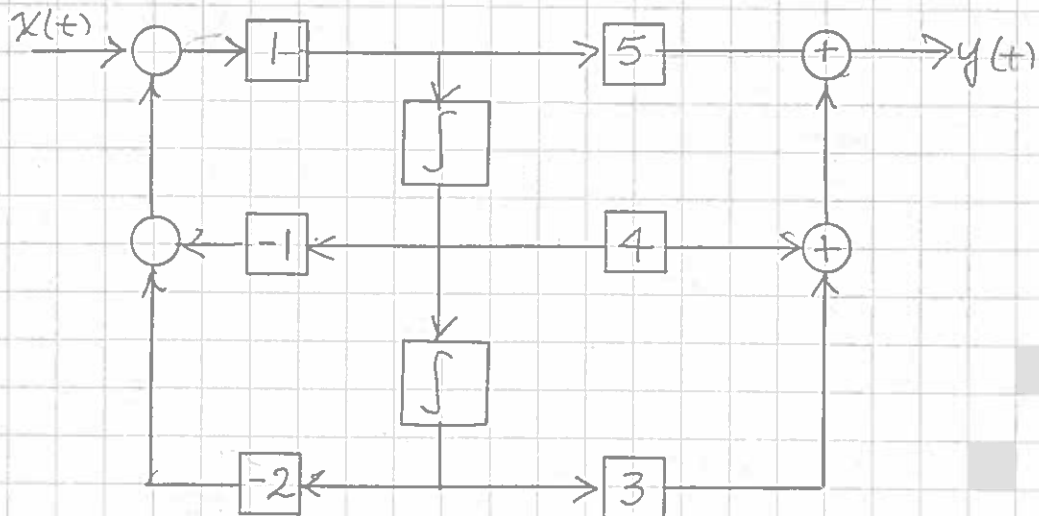
(a)

(b)

$$\frac{d^2 y}{dt^2} = 2 \frac{d^2 x}{dt^2} + \frac{dx}{dt} + 3y$$

PROBLEM 3.34

(a) Redraw the system diagram as:

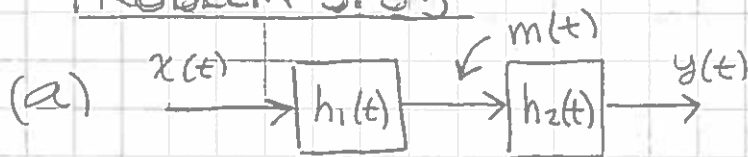


(b) It can be seen that this is a Direct Form II System diagram.

(a) From the diagram: $a_2 = 1, a_1 = 1, a_0 = 2$
 $b_2 = 5, b_1 = 4, b_0 = 3$

$$\therefore \frac{d^2 y(t)}{dt^2} + \frac{dy(t)}{dt} + 2y(t) = 5 \frac{d^2 x(t)}{dt^2} + 4 \frac{dx(t)}{dt} + 3x(t)$$

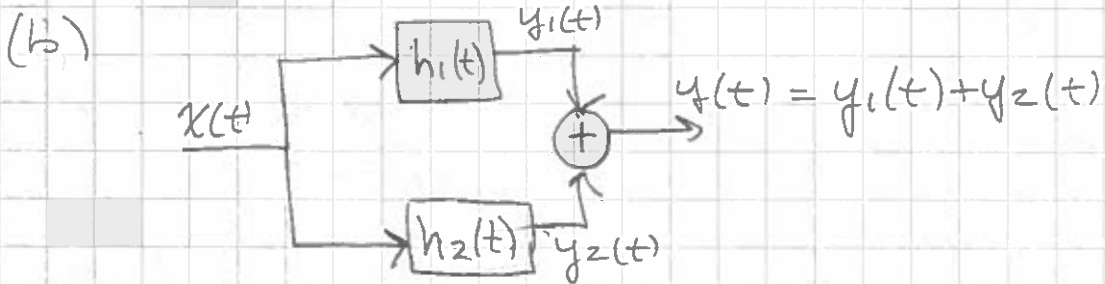
PROBLEM 3.35



$$m(t) = \mathcal{X}(t) H_1(s)$$

$$y(t) = H_2(s) m(t) = H_2(s) H_1(s) \mathcal{X}(t) = H(s) \mathcal{X}(t)$$

$$\therefore H(s) = H_1(s) H_2(s)$$



$$y_1(t) = H_1(s) \mathcal{X}(t) \quad , \quad y_2(t) = H_2(s) \mathcal{X}(t)$$

$$y(t) = [H_1(s) + H_2(s)] \mathcal{X}(t) = H(s) \mathcal{X}(t)$$

$$H(s) = H_1(s) + H_2(s)$$

PROBLEM 3.36

(a) From solution to Problem 3.12(a):

$$h(t) = h_1(t) * h_2(t) + h_1(t) * h_3(t) * h_4(t) + h_4(t) * h_5(t)$$
$$y(t) = h(t) * X(t) \Rightarrow y_{ss}(t) = H(s) X(t)$$
$$H(s) = H_1(s) H_2(s) + H_1(s) H_3(s) H_4(s) + H_4(s) H_5(s)$$

(b) From the solution to Problem 3.13(a):

$$h(t) = h_1(t) * h_2(t) + h_1(t) * h_3(t) * h_4(t) + h_1(t) * h_3(t) * h_5(t)$$
$$y(t) = h(t) * X(t) \Rightarrow y_{ss}(t) = H(s) X(t)$$
$$H(s) = H_1(s) H_2(s) + H_1(s) H_3(s) H_4(s) + H_1(s) H_3(s) H_5(s)$$

(c) From the solution to Problem 3.26:

$$y(t) = h_1(t) * X(t) - h_1(t) * h_2(t) * y(t)$$

let $m(t) = h_2(t) * y(t)$

then $y(t) = h_1(t) * [X(t) + m(t)]$

$$y_{ss}(t) = H_1(s) [X(t) + m(t)]$$

$$m_{ss}(t) = H_2(s) y_{ss}(t)$$

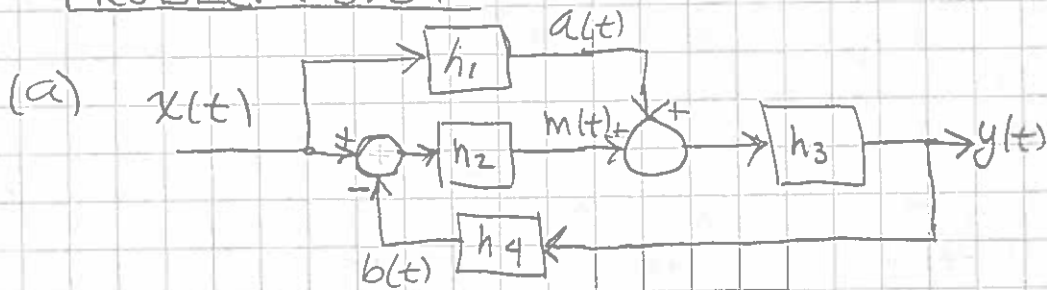
$$\Rightarrow y_{ss}(t) = H_1(s) X(t) + H_1(s) H_2(s) y_{ss}(t)$$

$$[1 + H_1(s) H_2(s)] y_{ss}(t) = H_1(s) X(t)$$

$$y_{ss}(t) = \frac{H_1(s)}{1 + H_1(s) H_2(s)} X(t) = H(s) X(t)$$

$$H(s) = \frac{H_1(s)}{1 + H_1(s) H_2(s)}$$

PROBLEM 3.37



$$a(t) = h_1(t) * x(t)$$

$$b(t) = h_4(t) * y(t)$$

$$m(t) = h_2(t) * [x(t) - b(t)] = h_2(t) * x(t) - h_2(t) * b(t)$$

$$= h_2(t) * x(t) - h_2(t) * h_4(t) * y(t)$$

$$y(t) = h_3(t) * [a(t) + m(t)]$$

$$= h_3(t) * h_1(t) * x(t) + h_3(t) * h_2(t) * x(t) - h_3(t) * h_2(t) * h_4(t) * y(t)$$

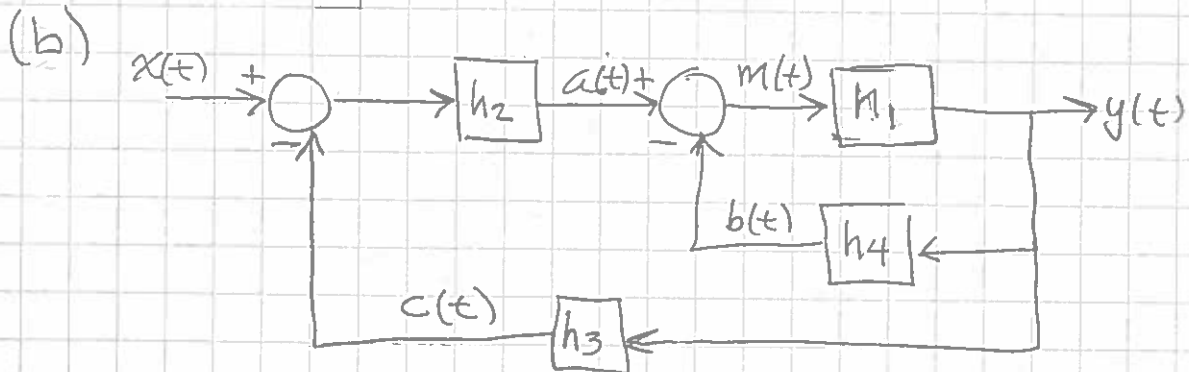
$$= h_3(t) * [h_1(t) + h_2(t)] * x(t) - h_3(t) * h_2(t) * h_4(t) * y(t)$$

$$y_{ss}(t) = H_3(s) [H_1(s) + H_2(s)] x(t) - H_3(s) H_2(s) H_4(s) y_{ss}(t)$$

$$y_{ss}(t) = \frac{H_3(s) [H_1(s) + H_2(s)]}{1 + H_3(s) H_2(s) H_4(s)} x(t) = H(s) x(t)$$

$$H(s) = \frac{H_3(s) [H_1(s) + H_2(s)]}{1 + H_3(s) H_2(s) H_4(s)}$$

PROBLEM 3.37 (continued)



$$a(t) = h_2(t) * [x(t) - c(t)]$$

$$m(t) = a(t) + b(t)$$

$$b(t) = h_4(t) * y(t)$$

$$c(t) = h_3(t) * y(t)$$

$$\therefore a(t) = h_2(t) * x(t) - h_2(t) * h_3(t) * y(t)$$

$$\begin{aligned} m(t) &= h_2(t) * x(t) - h_2(t) * h_3(t) * y(t) - h_4(t) * y(t) \\ &= h_2(t) * x(t) - [h_2(t) * h_3(t) + h_4(t)] * y(t) \end{aligned}$$

$$y(t) = h_1(t) * m(t)$$

$$= h_1(t) * h_2(t) * x(t) - h_1(t) * [h_2(t) * h_3(t) + h_4(t)] * y(t)$$

$$y_{ss}(t) = H_1(s) H_2(s) X(t) - H_1(s) [H_2(s) H_3(s) + H_4(s)] y_{ss}(t)$$

$$y_{ss}(t) + H_1(s) [H_2(s) H_3(s) + H_4(s)] y_{ss}(t) = H_1(s) H_2(s) X(t)$$

$$y_{ss}(t) = \frac{H_1(s) H_2(s)}{1 + H_1(s) [H_2(s) H_3(s) + H_4(s)]} X(t)$$

$$= H(s) X(t)$$

$$\therefore H(s) = \frac{H_1(s) H_2(s)}{1 + H_1(s) [H_2(s) H_3(s) + H_4(s)]}$$